



AR Monitoring System

By: Arbaaz, Sam, Patrick, Nipun, Dheeraj, Ben

Group: Dec1714

Client: Andrew Guillemette

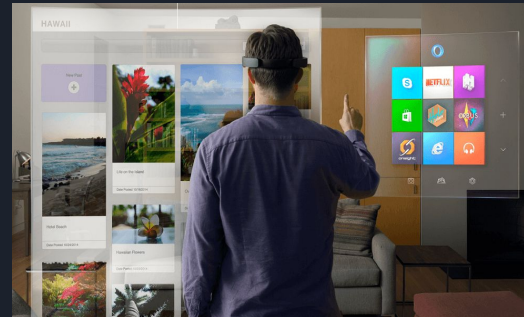
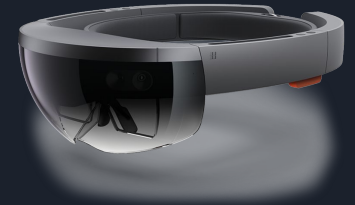
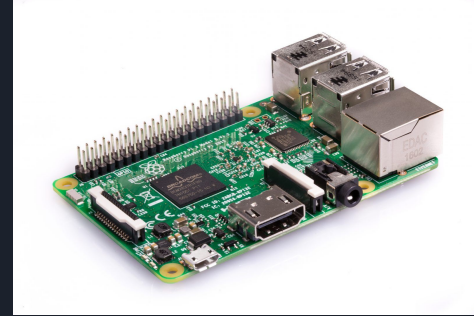
Project Statement

- AR monitoring solution to remotely track and monitor worksite vehicles
- View a worksite and current vehicle operations
- Personal identification for vehicle usage
- Updated from last semester's design



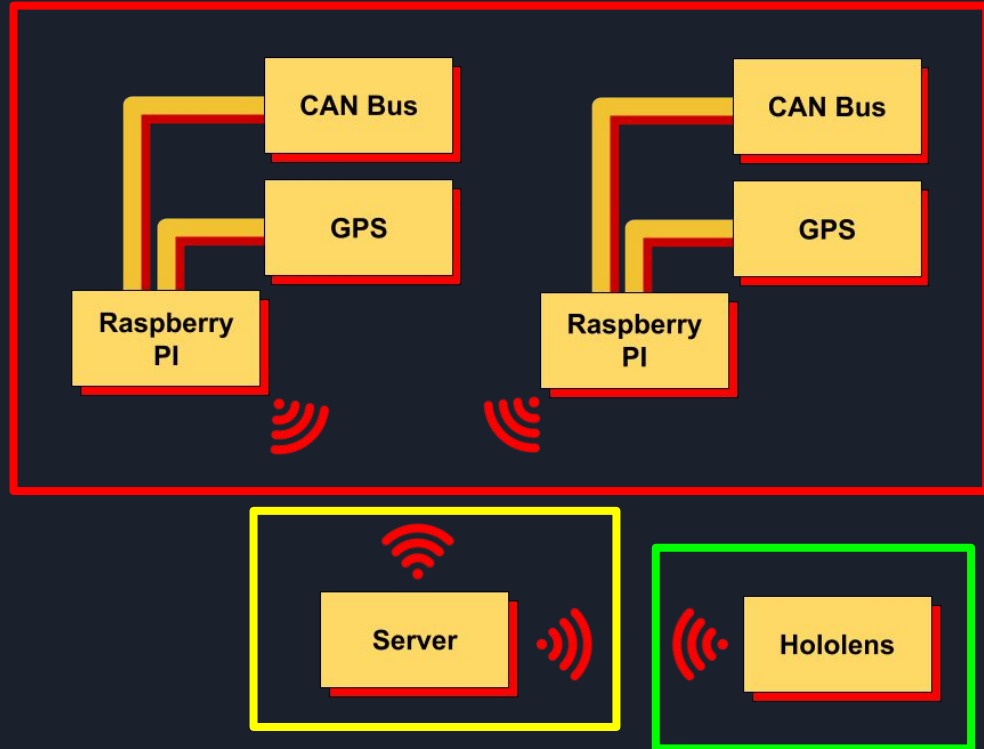
Technology

- **Raspberry Pi**- A low cost, mini computer that uses a standard keyboard and mouse.
- **HoloLens**- The first self-contained, holographic computer, engage with your digital content and interact with holograms in the world around you.
- **AR** - Augmented reality (AR) technologies are used to create a blend of virtual and real environments.



Team Roles & Responsibilities

- Arbaaz: Team Leader
- Patrick: Web Manager
- Pi/CAN/GPS
 - Arbaaz
 - Ben
 - Sam
- HoloLens
 - Dheeraj
 - Patrick
 - Nipun
- Server
 - Nipun
 - Dheeraj



Spring Semester Summary

- Gimbal/Camera Control
- HoloLens map
- Groundwork for Communications



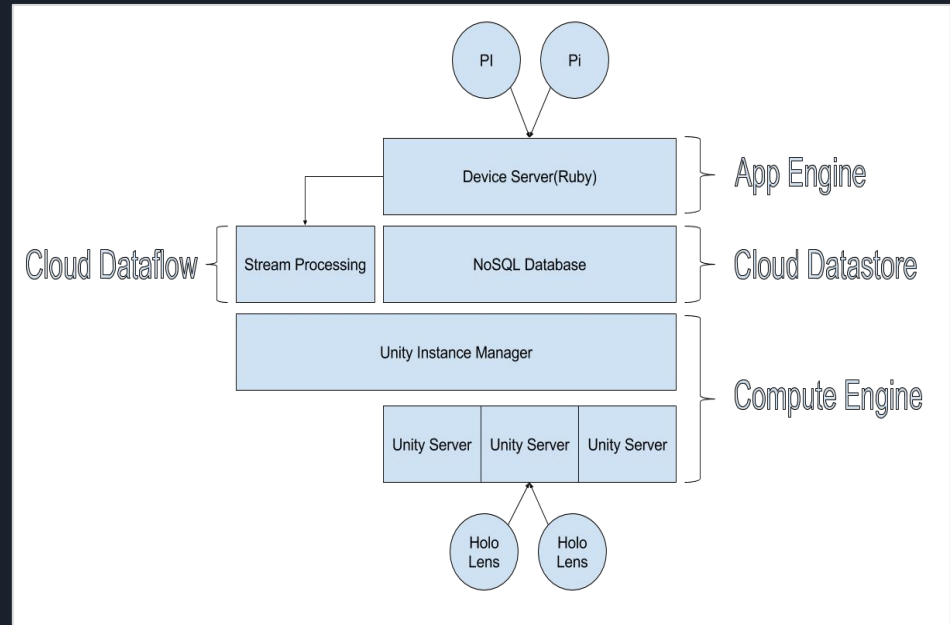
Semester 2 Hardware Changes

- New focus
- Different parts
 - CAN Shield
 - GPS Receiver



Semester 2 Software Changes

- New system design
- Communications protocol
- Platform independent libraries





Deliverables

- Hardware
 - GPS Tracking
 - CAN Bus information
 - Wireless Connectivity
 - Server Access
- Software
 - Platform independent connectivity
 - Data Visualization
 - Customizable placement
 - VFX and Interactivity



Design: Functional

- Ability to view monitored machine on map using HoloLens app
- Ability to view a custom area map on the HoloLens app
- Ability to asses machine status from HoloLens app
- Ability to monitor desired CAN bus output from the HoloLens app

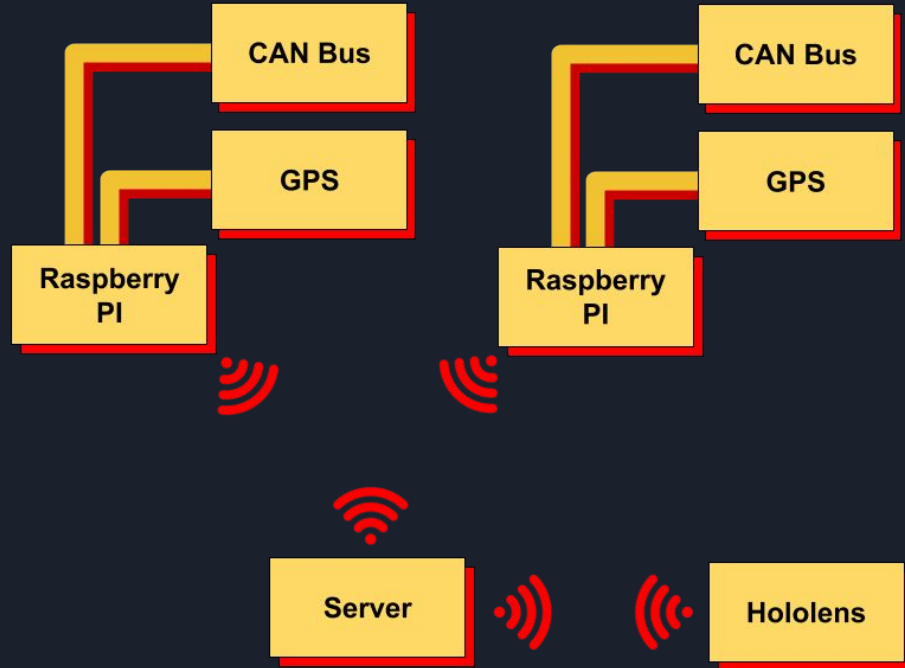


Design: Non-Functional

- The software should be able to be adapted for many different purposes and inputs
- The software should be secure
 - Unauthorized devices should not be able to feed false data nor should they be able to view device data

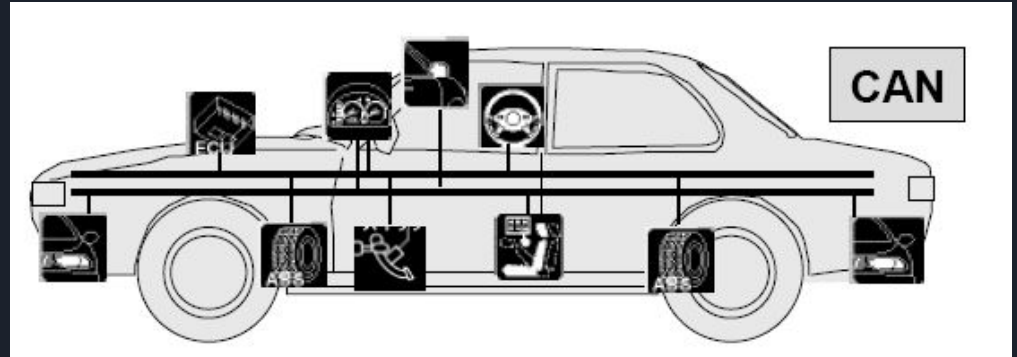
Conceptual Sketch

- 3 main Components
 - Server
 - HoloLens
 - PI / CAN Bus / GPS
- Wi-fi connectivity



Hardware Testing

- Hardware
 - GPS Tracking
 - Read requested CAN Bus info
 - Server Communication
 - User Tracking



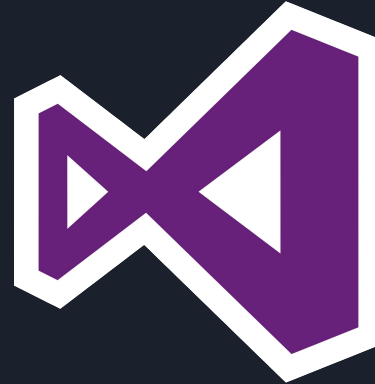


Software Testing

- HoloLens
 - Editor Scripts
 - Dummy devices
 - Real Time 3D models
- Raspberry Pi
 - Test scripts
 - Receive Hardware data

Semester 1 Challenges

- Limited Documentation
- Lack of Analog I/Os
- Python
- Video Type
- Unity/Visual Studio
- New Technology



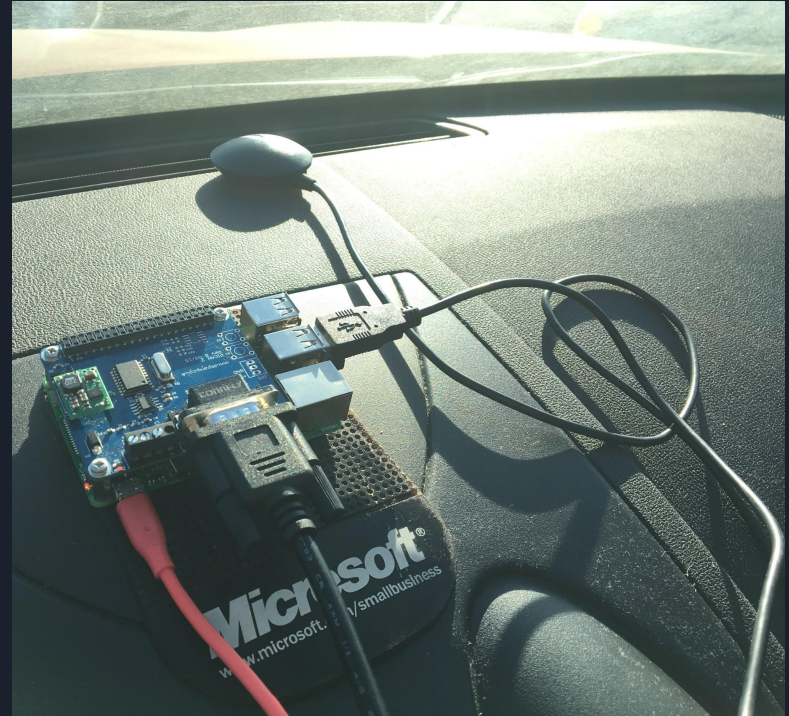
Semester 2 Challenges

- Unity/Visual Studio
- Hardware change
- Server Communication



Conclusion

- Effective proof of concept for benefits of AR monitoring
- Solution allows for supervisors to monitor real-time vehicle operations remotely
 - CAN Bus
 - GPS

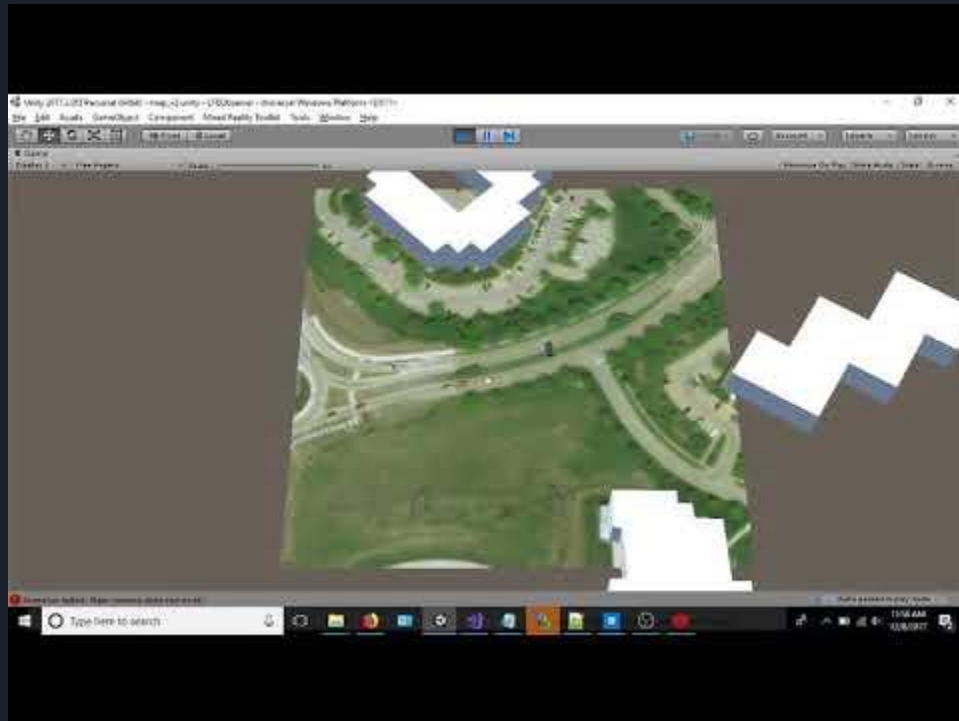




Conclusion (future work)

- Improvements upon HoloLens app
 - Graphical
 - Interface
- More accurate GPS
 - Global Navigation Satellite System
- Improvements to vehicle personnel identification
 - RFID
 - Miles Log
 - Time Log

Demo





Any
Questions?